

## Exercise for Optimal control – Week 5

Choose **2** problems to solve.

**Exercise 1.** A public company has in year  $k$  profits amounting to  $x_k$  SEK. The management then distributes  $u_k$  to the shareholders and invests  $x_k - u_k$  in the company itself. Each SEK invested in such way will increase the company profit by  $\theta > 0$  the following year so that

$$x_{k+1} = x_k + \theta(x_k - u_k).$$

Suppose  $x_0 \geq 0$  and  $0 \leq u_k \leq x_k$  so that  $x_k \geq 0$  for each  $k$ . The objective of the management is to maximize the total amount distributed to the shareholders over a period of  $N$  years, i.e.,

$$\max_{u_k} \sum_{k=0}^{N-1} u_k$$

subject to  $u_k \in [0, x_k]$ .

**Exercise 2.** Derive the complete value iteration procedure – with  $J_0 = 0$  – for the optimal control problem

$$\min \sum_{i=1}^{\infty} (x_i^\top Q x_i + u_i^\top R u_i)$$

under the constraint:

$$x_{k+1} = A x_k + B u_k.$$

(there is no constraint on  $u$ ).

*Hint: 1) Write  $J_k$ ,  $k \geq 1$  as  $J_k(x) = x^\top P_k x$ , and  $u_k = -K_k x$  where*

$$u_k \in \arg \min_u \{x^\top Q x + u^\top R u + J_k(Ax + Bu)\}.$$

*2) find the iteration formula for  $K_k$  and  $P_k$ . Don't forget the boundary conditions.*

**Exercise 3.** Show that free terminal time optimal control problem can be turned into a fixed terminal time problem. Why is this useful in numerical computation? *Hint: consider a rescaling of time  $\tau = \frac{t}{t_f}$ .*

**Exercise 4.** Derive the maximum principle for the Bolza form cost by utilizing the maximum principle for the Mayer form.

**Exercise 5.** Prove the maximum principle for the case that  $t_f$  is free. You may consider the Mayer type problem. *Hint: all the necessary conditions for  $t_f$  fixed are still necessary. One only needs to derive the additional condition that  $H \equiv 0$  along the optimal solution. You can either use the trick in Ex2 or consider a new variation in  $t_f$ :  $x_\epsilon(t_f + \epsilon\mu) \in \Omega_1$  where  $x_\epsilon(\cdot)$  is some needle variation and  $\mu$  some real number.*